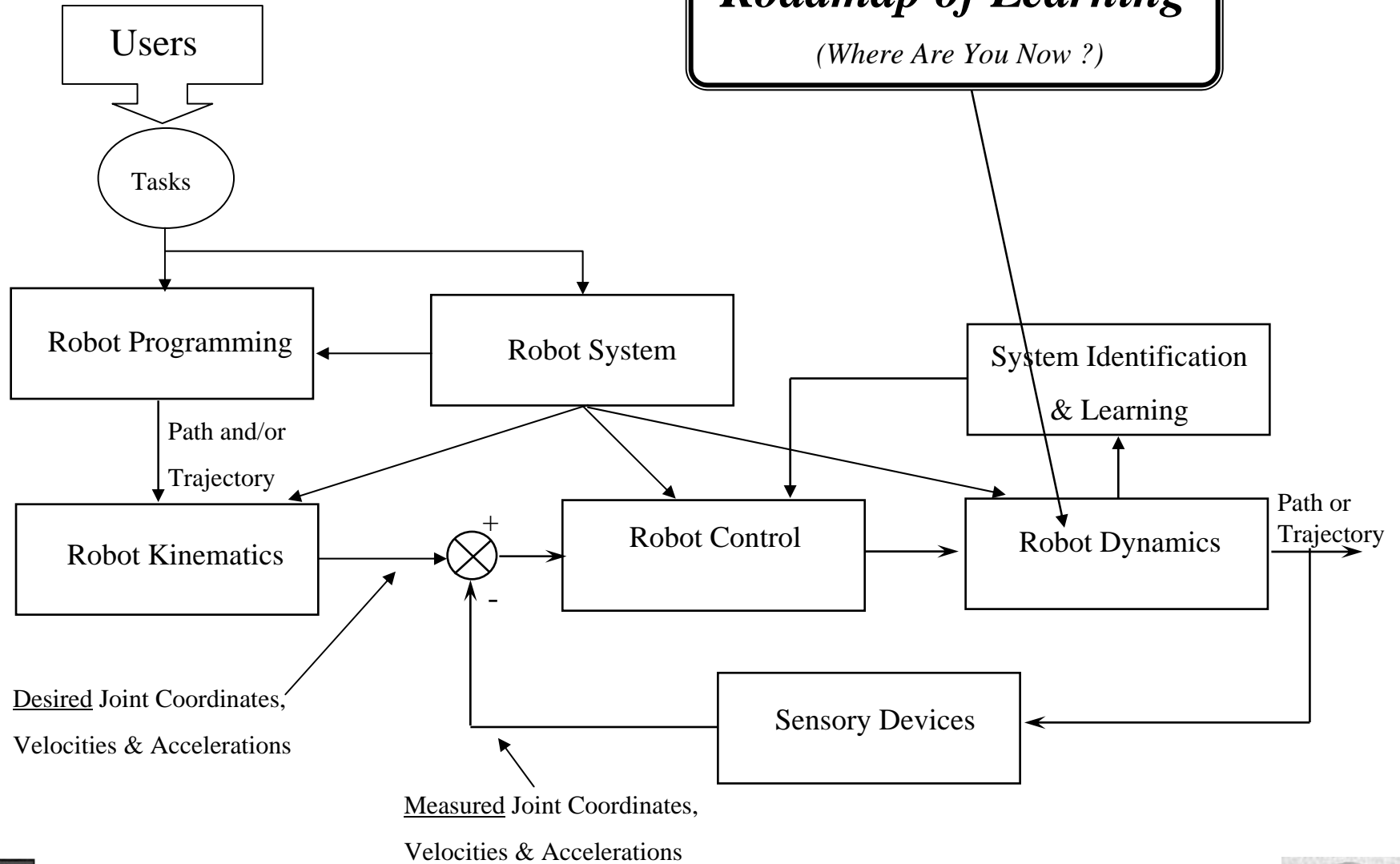


Roadmap of Learning

(Where Are You Now ?)



CONTENT

Chapter 5: Robot Statics and Dynamics

5.1 Prerequisite of Dynamics

5.2 Principle of Virtual Work

5.3 Robot Statics

5.4 Euler-Lagrange Formulation

5.5 Newton-Euler Formulation

5.6 Forward Dynamics

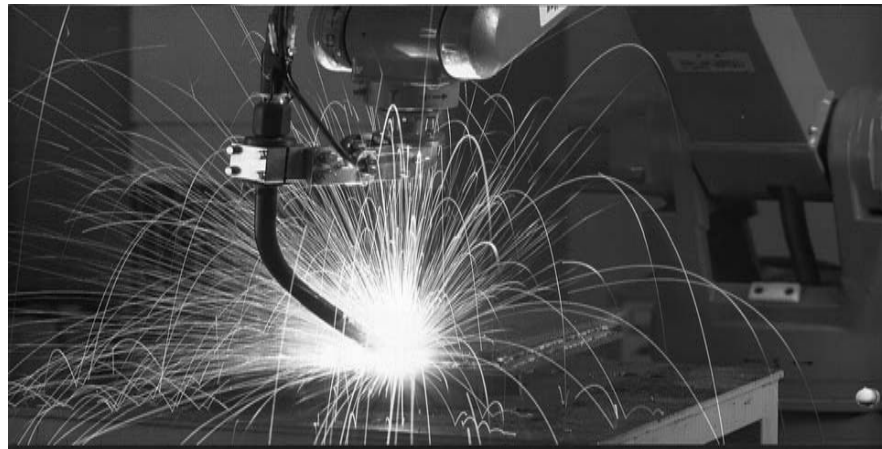
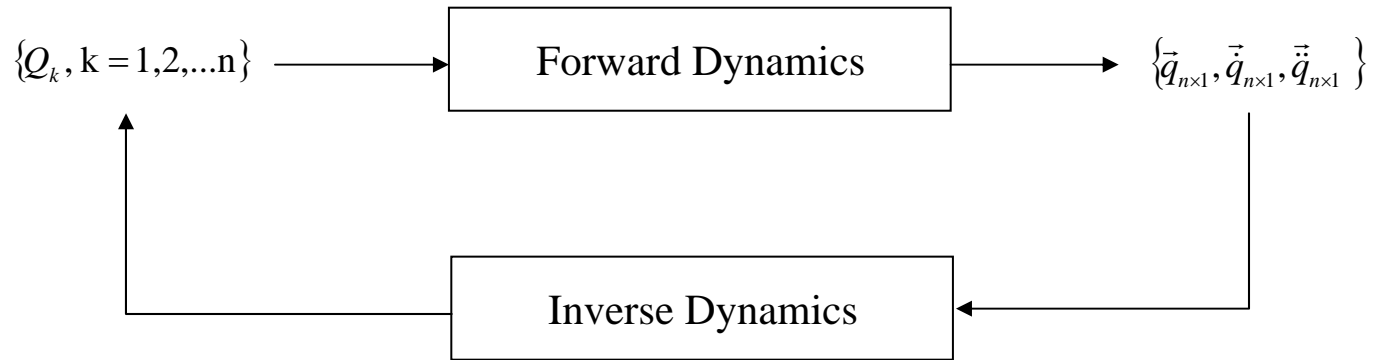
5.7 Inverse Dynamics

Have Learnt

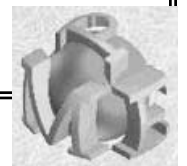
To Learn



Concerns of Robot Dynamics



Example 1:



Example 2:



Example ...:

